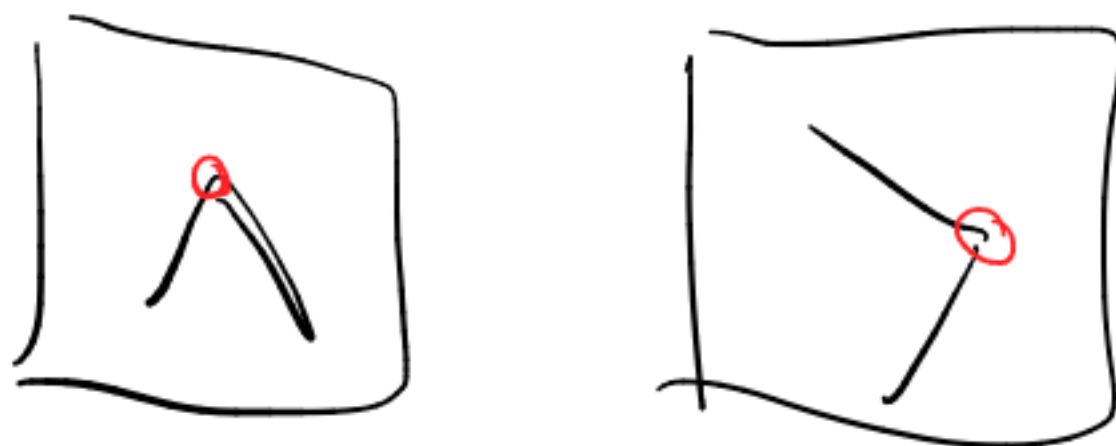


- Invarianza di Rotazione

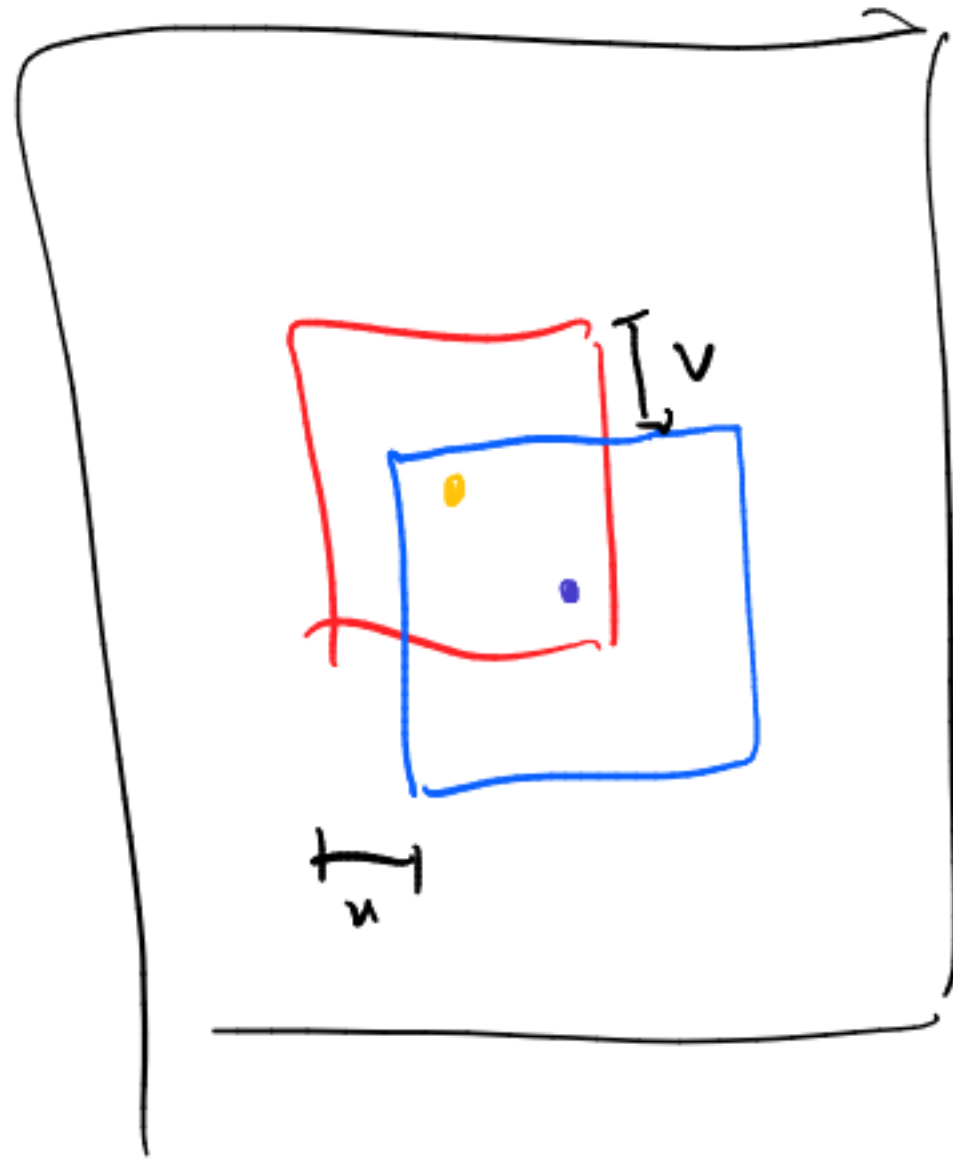


- Invarianza di Intensità



- Invarianza di scala





$$f(x) \approx a + b(x - x_0) + c(x - x_0)^2$$

$$f(x) = \underbrace{f(x_0)}_a + \underbrace{\frac{d}{dx} f(x_0)}_b (x - x_0) + \underbrace{\frac{1}{2} \frac{d^2}{dx^2} f(x_0)}_c (x - x_0)^2$$

$$f(\delta x, \delta y) \approx f(0,0) + \begin{bmatrix} \frac{\partial f}{\partial x}(0,0) \\ \frac{\partial f}{\partial y}(0,0) \end{bmatrix}^T \begin{bmatrix} \delta x \\ \delta y \end{bmatrix}$$

$$\frac{1}{2} \begin{bmatrix} \frac{\partial^2 f}{\partial x^2}(0,0) & \frac{\partial f}{\partial x} \frac{\partial f}{\partial y}(0,0) \\ \frac{\partial f}{\partial y} \frac{\partial f}{\partial x}(0,0) & \frac{\partial^2 f}{\partial y^2}(0,0) \end{bmatrix} \begin{bmatrix} \delta x \\ \delta y \end{bmatrix}$$

$$F(0,0) = 0$$

$$E_u(u,v) = 2 \int_{xy} w(x,y) \left[I(x+u, y+v) - I(x,y) \right] \frac{\partial I}{\partial u}(x+u, y+v)$$

$$E_u(0,0) = 0 = E_v(0,0)$$

$$E_{uu}(u, v) = \frac{\partial}{\partial u} \sum_{x, y} w(x, y) \left[I(x+u, y+v) - I(x, y) \right] \frac{\partial I}{\partial u}(x+u, y+v)$$

$$= \sum_{x, y} w(x, y) \frac{\partial}{\partial u} I(x+u, y+v) \cdot \frac{\partial I}{\partial u} I(x+u, y+v)$$

$$= \sum_{x, y} w(x, y) I_x^2(x+u, y+v)$$

$$E_{uu}(0, 0) = \sum_{x, y} w(x, y) I_x^2(x, y)$$



